12 Reasons
Why High-Impact Researchers Choose The Dragonfly Confocal

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ABSTRACT

Dragonfly is a high-performance multi-modal imaging platform. In this article, we focus on Dragonfly’s multi-point scanning confocal imaging performance and compare it to single point scanning, which has become the dominant technology over the last 30 years. We show that Dragonfly exceeds or matches the performance of point scanners in all important aspects. As life science research accelerates and demands greater throughput for deeper study, we suggest the community should consider this new and powerful platform wherever there is a need for fast, sensitive, high resolution confocal imaging.
**REASON ONE: Speed**

**Dragonfly is ten to twenty times faster**

Speed is important in scientific imaging applications for several reasons. These include increasing throughput to build statistical confidence; dealing with larger specimens e.g. embryos and tissues where montage imaging is needed; access to fast biology in living specimens – e.g. see figure 1.

Point scanning confocal microscopes, like those provided by the major microscope companies, have become the de facto standard for fixed cell and tissue imaging and they can be stretched to some live cell work. But sequential scanning of a single beam through millions or billions of voxels (volume elements) is a laborious process with major disadvantages (Pawley 2000). In contrast the multi-point scanning methodology used in Dragonfly, scans thousands of micro-beams to deliver parallel confocal imaging. In head to head comparisons with the latest point scanners, Dragonfly delivers 10–20 times faster volumetric imaging and, as we shall show, this is achieved with the highest quality.

Perhaps surprisingly, the speed comparison holds true even for resonant scanning systems, because the speed limitation cannot be overcome simply by scanning a single beam faster. The ultimate limitation boils down to the number of photons that can be collected from a diffraction limited volume in a single voxel dwell time (Tsien et al 2006): faster single beam scanning requires either increasing beam power, or frame averaging for adequate signal to noise ratio. The former rapidly bleaches fluorophores with damaging side-effects (phototoxicity), while the latter slows the acquisition rate. Typical acquisition rates for resonant scanners are 512x512 voxels at 30 frames per second (fps).

**Dragonfly’s multi-point scanning is based on micro lens spinning disk (MSD) technology. MSD utilizes two disks mounted on a shared motor spindle: one contains an array of micro lenses disposed on a spiral pattern, while the other contains pinholes aligned on an identical pattern. This arrangement allows the micro lens to focus collimated laser light through the pinholes in an efficient manner, while also reducing background. In contrast single pinhole disk systems, the laser throughput is determined only by the open area fraction of the pinholes, and this leads to very low efficiency and increased laser background.**

**Key features of Andor's MSD technology include high scan rates, no scanning dead time and use of extremely sensitive detectors, which make the best of the low background, as we shall see later. Frame rate is controlled by camera exposure time and laser synchronization. During an exposure, signal is integrated over one or more scans. Dragonfly’s underlying scan rate is 400 scans per second, making it possible to image with incremental exposures of 2.5 ms. Paired with a scientific CMOS camera, Dragonfly can deliver up to 400 fps at 512x512 resolution.**

While point-scanners can be configured for parallel detection of multi-channel fluorescence to improve speed, results may be negatively impacted by spectral cross-talk between fluorophore channels and increased photobleaching. To correct for this cross-talk, “spectral detection” (Dickinson et al 2001) can be used to separate overlapping fluorophore emissions. However, this results in reduced signal to noise ratio (SNR) because the signal must be split over an array of detectors and each detector element has an associated read noise. The imaging rate must usually be slowed to achieve adequate SNR for the linear unmixing algorithms to do their job. But with sufficient SNR, these tools can perform extremely well.

The smartest approach to minimizing spectral cross-talk in a multi-channel MSD instrument is to use pairwise simultaneous acquisition where the excitation and emission wavelengths are well separated. For example, a four-wavelength experiment might proceed with laser excitation of pairs 405 & 560 followed by 488 & 640 nm to achieve low cross-excitation and higher speed. In this scenario, SNR is not impacted and cross talk is minimized. Dragonfly supports this kind of simultaneous dual-channel imaging with two cameras, providing a potential frame rate of 800 frames (400 image pairs) per second.

Figure 1. Movie shows orthogonal projections of a crawling c. elegans worm, which was tracked and corrected to remove coarse center-of-mass motion so that it appears stationary except for distortions involved with locomotion. Dual-channel simultaneous imaging of red (mNeptune: pan-neuronal) and green (GCaMP6: calcium) channels was achieved with a pair of Andor Zyla 4.2 plus sCMOS cameras with Andor Dragonfly high speed confocal. A 60x silicone oil objective was used on Dr Venkatchalam’s homebrew upright microscope. The original image was acquired binned 2x: 512x1024 super pixels. Each exposure is 10 ms, with 20 slices per volume for a volumetric frame-rate of ~5 Hz and 20 second duration. The data has been rescaled (debleached) to fill the full grey range, and the camera background has been subtracted. No additional processing has been done. **Data courtesy of Dr Vivek Venkatchalam. Department of Physics, Northeastern University, Boston, MA.**
**REASON TWO: Sensitivity**

Dragonfly is 3–5 times more sensitive

Sensitivity is a fundamental parameter of all microscope imaging systems. It determines the minimum detectable signal for a given excitation intensity. Critical factors affecting sensitivity are quantum efficiency (QE) and read noise (RN) of the detector as well as instrumental and specimen background. In two-dimensional detectors, as the limits of performance are reached, fixed pattern noise (FPN) becomes a limiting factor to sensitivity. FPN describes the small variations in sensitivity across the sensor material, giving rise to low level structured background, sometimes referred to as photo-response non-uniformity (PRNU). Camera manufacturers go to great lengths to correct PRNU and minimize its impact.

The theoretical limit to SNR is shot noise resulting from the statistical nature of photon emission. The absolute maximum SNR is \( N^{1/2} \) or square root of the number of detected photons, so the more photons that can be gathered, the better the SNR. QE measures the efficiency of a detector to convert photons incident upon it, to photo-electrons (signal). Instrumental SNR for a given number of incident photons, \( N \) can therefore be summarized as follows:

\[
\text{SNR} = \frac{(N\times\text{QE}-\text{mean}(\text{background}))}{(N\times\text{QE}+\text{FPN}^2+\text{RN}^2+\text{var}(\text{background})))^{1/2}} \quad \text{Equation 1}
\]

Point scanners utilize photomultiplier tubes (PMTs) for detection and consequently are limited by the QE of the photocathode materials used in these devices. Typical QE values of PMTs in high end instruments are 10–40% depending on wavelength and selected material (Hamamatsu 2007). Gallium Arsenide Phosphide (GaAsP) photocathodes provide the highest QE, exceeding 25% from 400–650 nm with rapid decline outside this region and a peak of 40% at 540 nm (see Figure 2). The PMT relies on electron multiplication through a dynode chain and this introduces multiplicative noise (MN). Assuming good design, MN increases noise by a factor of around 1.25, which is equivalent to reducing QE by a factor of MN\(^2\) or about 1.56. Hence the effective peak QE of a GaAsP detector is approximately 26%. Moreover, the system SNR is inversely proportional to the square root of the detection circuit bandwidth, which provides another challenge for speeding acquisition with resonant scanning, where bandwidth increases by a factor of 10 or more.

A more recent development is the use of hybrid detectors (HyD) (Hamamatsu 2007), which combine GaAsP photocathode with direct acceleration of the resulting electrons into a silicon avalanche diode (AD). The resulting gain is much lower than a PMT and is highly dependent on temperature, but the multiplication noise of a dynode chain are reduced and HyD has benefits in terms of pulse height repeatability and stability. Although these detectors are often quoted for use in photon counting mode (PCM), it is worth pointing out that practical results from PCM yield photon counts of a few tens of event per scan, with shot noise this leads to poor SNR and typically demands multiple scans for signal accumulation. Moreover, insufficient PCM bandwidth results in pulse pile-up and non-linearity (see Reason Four).

Dragonfly utilizes the latest generation back side illuminated (BSI) electron multiplying charge coupled devices (EMCCD) and Scientific Complementary Metal Oxide Semiconductor (sCMOS) sensors with peak QEs between 82% and 95% and broad spectral profiles (300–950 nm). The effective read noise of an EMCCD is estimated from output amplifier read noise divided by the EM Gain. Thus, Andor’s iXon Ultra 888 can deliver read noise of < 0.2 electrons rms (root mean square) (Basden 2015). EMCCD’s show multiplicative noise (MN) in the gain register, like PMTs, but thanks to the very low effective read noise, deliver single photon sensitivity. EMCCD MN is typically 1.41, resulting in an effective peak QE of about 48%, but this is still almost twice that of the best PMT with a substantially wider spectral range (see Figure 2).

SCMOS detectors were first introduced by Andor in 2009 (Coates et al 2009). The major benefit of sCMOS is the ability to implement sophisticated circuitry on the same chip as the photo sensor array. This allows parallel readout and digitization of all rows of the sensor. For example, a 2048x2048 sensor (4 MPixel) can be read at 100 fps, while each pixel is addressed at only 200 kHz and thus a very low readout noise can be achieved e.g. 1–2 electrons rms. Low read noise coupled with high QE gives Dragonfly a significant advantage over point scanners. In recent years Andor has increased this advantage, releasing the Sona family of back-illuminated sCMOS cameras with peak QE of 95%.

However, EMCCD remains the most sensitive detector at low signal levels (10–15 photons per pixel). In Figure 3, we compare EMCCD and sCMOS operating in Dragonfly under near identical imaging conditions, while increasing the exposure time and hence photon count, to illustrate relative imaging performance.
Comparing EMCCD and sCMOS detectors to PMT’s by effective QE, results in an advantage to Dragonfly of three to five times.

Figure 2. Detector performance sets the baseline for instrument sensitivity. Above left we show the QE of PMT’s vs EMCCD and sCMOS detectors. On the right, we account for multiplicative noise, which is modelled as a reduction in QE by the square of the noise factor. SCOMS sensors are dramatically more efficient and when shot noise (square root of signal) dominates read noise, they outperform even EMCCD. Both image sensors dramatically outperform photo-cathodes used in PMT devices.

Figure 3. iXon Ultra EMCCD and Zyla 4.2 plus sCMOS cameras were directly compared for sensitivity. Cameras were set up on the imaging ports of Dragonfly and were pixel size matched using imaging zoom: Zyla at 1X and iXon at 2X resulting in a pixel size of 6.5 µm. The same specimen was sequentially imaged onto each camera with exposures interleaved (Zyla:iXon:Zyla:iXon etc.) so that one camera was not substantially disadvantaged by bleaching. The “cross-over” where Zyla sCMOS delivers similar image SNR to EMCCD is around 20 photons per pixel. Sona Back illuminated sensors become dominant in the range 10-15 photons per pixel.
**REASON THREE: Background Rejection**

**Imaging thicker specimens**

Although QE is a critical to sensitivity, SNR and contrast can also be limited by non-specific background from the specimen as identified in Equation 1. Background contributes directly to the measurement noise-floor and impacts the detection limit. An instrument’s capability to reject such background is then a key parameter. The most demanding scenario, has a “sea of fluorescence” emitting in the out-of-focus volume of the specimen, excited by divergent beams from adjacent pinholes (Egner et al 2000). This is representative of auto-fluorescence in tissue specimens (see Figure 12), but may not be typical of many other specimens which are specifically labelled. Nonetheless, this scenario helps to compare performance between single point scanning and other technologies. In point scanners, there is only a single pinhole so there can be no cross-talk. In MSD and other multi-point scanners, cross-talk between pinholes sets the limit to contrast.

More specifically, pinhole size, spacing and objective magnification set the depth at which fluorescence from adjacent excitation volumes infiltrates neighbouring pinholes. Pinhole size and spacing (open area fraction) also determines the transmission of the pinhole disk, which sets contrast in the sea of fluorescence test. In older MSD, the transmission varies from 4% to 1% and at 60X the pinhole separation in specimen space is between 4 and 8 µm, so that cross-talk begins in specimens above 5 or 10 µm. Shimozawa et al (2013) used the sea of fluorescence test to evaluate the performance of different models of CSU, including multi-photon models. They plotted residual background fraction vs thickness of the sea of fluorescence and in Figure 4 we show their results for single photon performance of CSU models and extend the series for Dragonfly 40 and 25 µm pinholes. Clearly, Dragonfly is between two and ten times more capable at rejecting background in single photon MSD, but as you would expect does not match multi-photon MSD – not shown, but close to zero.

Point scanners show excellent performance in the sea of fluorescence test, but practical comparison with Dragonfly using real specimens yields somewhat surprising results. Slow scanning speed and high bleaching rates, combined with inferior sensitivity result in surprisingly poor imaging performance with thicker specimens. Many researchers have resorted to multi-photon point scanning with the associated high cost lasers and low efficiency of multi-photon excitation. Dragonfly offers an alternative and much faster solution which is attracting considerable interest. In practice, with specifically labelled thick specimens Dragonfly imaging performance has proven exceptional, routinely delivering high contrast in embryos and tissues hundreds of microns thick, as illustrated in Figure 5.
REASON FOUR: Resolution
Motorized camera zoom and pinholes support multiple objectives

Resolution can be defined in a number of ways, but each depends on the ability to differentiate between small features which lie close together in the specimen focal plane. In digital instruments, resolution depends not only on optical properties, but also the sampling density or effective pixel or voxel size. For a diffraction limited epi-fluorescence microscope the resolution limit is set by imaging wavelength and objective numerical aperture: to reach this limit the image must be sampled at a minimum of the Nyquist sampling interval (Heintzmann and Shepard 2007). Nyquist sampling is more easily achieved with high magnification objectives as shown in Table 1. Modern low magnification immersion objectives make this even more challenging as science demands visualization of large tissues, organoids and model organisms.

With the Dragonfly 500 series, three imaging port magnifications are provided: 1X, 1.5X and 2X. These allow the detector sampling to be adapted to different objectives. Table 1 shows the “strict” Nyquist lateral and axial sampling interval (dXStrict and dZStrict) for confocal imaging, to ensure that all spatial frequencies are sampled (Heintzmann and Sheppard 2007). This formulation is for a noise free system. In practice, noise will most strongly impact the highest frequencies, so we may choose to relax sampling and improve SNR, since the number of photons gathered per pixel increases with the square of the pixel dimension. High SNR is desirable when using deconvolution, but we must not relax sampling too much or we will lose the high frequency information which we try to recover in the process. Fusion’s ClearView™ deconvolution module makes use of a graphics processing unit (GPU) which executes the necessary mathematical functions in a highly parallel manner, achieving 10–20 times faster processing than central processing unit (CPU) based approaches.

Confocal resolution depends not only on detector sampling, but also the illumination/detection pinhole size, as summarized graphically in Figure 6. Equation 2 describe the lateral full width half maximum (LFWHM) response to a point object in the confocal microscope with a point detector. Equation 3 describes the axial (AFWHM) response to a planar object. Equation 4 shows a good approximation of the relationship between AFWHM and pinhole size in Airy Units (AU) (Wilson 2011).

\[
\text{LFWHM} = 0.37 \frac{\lambda}{NA}
\]

Equation 2

\[
\text{AFWHM} = 0.67 \frac{\lambda}{n\sqrt{n^2-NA^2}}
\]

Equation 3

\[
\text{AFWHM (AU)} = 0.67 \frac{\lambda}{n\sqrt{n^2-NA^2}} \left(1+1.47\text{AU}^3\right)^{1/3}
\]

Equation 4

To scale lateral and axial resolution onto the same axis in Figure 6, take the reciprocal of AFWHM(AU) and LFWHM(AU) and multiply by LFWHM from equation 2. The x axis of Figure 6 is calibrated in Airy units: 1 AU = 1.22/NA, and corresponds to the diameter of the first zero in the Airy disk produced when a lens of numerical aperture NA images a point object.

Figure 6. Graphic summarizing normalized Signal, Lateral and Axial Resolution in the confocal microscope. As the pinhole size is reduced, axial and lateral resolution improve. The profiles labelled 50, 40 and 25 µm show the loci of pinholes of that dimension and their equivalent Airy-scaled size as wavelength varies – for a 60X/1.2 Water objective. The normalized pinhole radius is inversely proportional to imaging wavelength, scaled on the right-hand Y axis. The Dragonfly 40-µm pinhole is near optimum (1 AU) at this magnification, while the 25 µm pinhole achieves enhanced axial and lateral resolution at the cost of signal.

<table>
<thead>
<tr>
<th>Obj</th>
<th>NA</th>
<th>n</th>
<th>ex</th>
<th>em</th>
<th>dXNr</th>
<th>dZNr</th>
<th>Mag sCMOS</th>
<th>Mag iXon</th>
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<tr>
<td>100</td>
<td>1.4</td>
<td>1.51</td>
<td>488</td>
<td>525</td>
<td>0.07</td>
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<td>0.89</td>
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<td>488</td>
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<td>20</td>
<td>0.9</td>
<td>1.33</td>
<td>488</td>
<td>525</td>
<td>0.11</td>
<td>0.58</td>
<td>2.87</td>
<td>5.74</td>
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</table>

Table 1. Shows “Nyquist” pixel size for different objectives. dXNr and dZNr show the recommended sampling interval at the specimen plane in order to trade off signal for noise and retain high frequency content in the resulting image. R Mag sCMOS and R Mag iXon indicate the magnification required in the detection path to approach Nyquist sampling at the detector plane. Note sCMOS physical pixel size is 6.5 um, while iXon 888 is 13 um.
For pinholes below 0.5 AU, normalized lateral and axial resolutions are close to their maxima, with lateral resolution about 1.3–1.4 times the wide field resolution, described by various criteria, including Abbe and Rayleigh limits. With a pinhole of 1.2 AU or larger, the lateral resolution plateaus at the Abbe limit ($\lambda/2NA$) with a normalized value of ~0.72, while the axial resolution continues to roll-off with larger pinholes.

The widely accepted “best compromise” for pinhole size, trading resolution and signal, is about 1.0 AU. Larger pinholes offer little benefit because ~70% of the signal (energy) is already captured in the Airy disk and increasing pinhole size mainly passes more out-of-focus light, degrading contrast. Smaller pinholes can improve lateral and axial resolution to a point, and when used with deconvolution can exceed the Abbe limit by a factor of 1.3 to 1.4 – see Figure 7.

A key design goal for Dragonfly was to match the resolution of point scanners and provide flexibility for different objectives. Camera zoom enables Nyquist sampling to be maintained for a range of objectives as illustrated in Table 1. The optimum pinhole for a 60X/1.2 W lens is around 40µm, while optimum for a 40X/1.0 W lens is about 25 µm. At longer wavelengths, Dragonfly’s NIR imaging capabilities benefit from the 25 µm pinhole for lower magnifications such as 25X Water or Multi-immersion objectives which are often recommended for imaging thick and cleared tissue.

Beyond the purely optical performance, GPU-accelerated deconvolution provides both lateral and axial resolution enhancement. The reduction in out of focus haze enhances contrast and enables measurements that were previously difficult or impossible. Fusion’s deconvolution is fast and can be interleaved with acquisition to ease its use and optimize workflow. Resolution test results are shown Table 2 and Figures 7 and 8.

### Table 2. The matrix for comparison of imaging performance with the Dragonfly in widefield and confocal with 40 µm pinhole before and after deconvolution. 25 µm data will be added to this table in the next revision of the white paper. Measurements were made with MetroloJ imageJ plugin for PSF analysis. 100 nm beads fluorescent were imaged at 488 nm laser excitation, with a Zyla 4.2 plus, 1X camera zoom and Nikon 60X/1.4 plan apo oil lens. Z step was 0.1 µm.

<table>
<thead>
<tr>
<th>100 nm beads @ 488 nm PSF - Typical</th>
<th>WF Raw</th>
<th>WF + Decon</th>
<th>WF Theory</th>
<th>DFly40 Raw</th>
<th>DFly40 + Decon</th>
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</thead>
<tbody>
<tr>
<td>Lateral FWHM (nm)</td>
<td>245</td>
<td>185</td>
<td>218</td>
<td>238</td>
<td>141</td>
</tr>
<tr>
<td>Axial FWHM (nm)</td>
<td>573</td>
<td>386</td>
<td>510</td>
<td>523</td>
<td>252</td>
</tr>
</tbody>
</table>
GPU-accelerated Deconvolution integrated within the acquisition engine delivers throughput advantages for Dragonfly workflow and delivers exceptional resolution.

7 A Before and after iterative deconvolution with Fusion’s ClearView-GPU. Human neuroblastoma cell expressing SH-SY5Y amyloid precursor protein. Blue: Nucleus (Hoechst), CellLight Lysosomes-GFP, CellLight early endosomes-RFP. Significant improvements in contrast and lateral resolution are evident. Courtesy Ms. Zahra Afghah and Drs. Jonathan D. Geiger and Xuesong Chen, Uni. North Dakota. In this maximum intensity projection (MIP) axial resolution enhancement is not obvious, but it can be one of the most striking effects as shown in Figure 8.

8 A Daisy pollen maximum intensity projection of 488 and 561 channels before and after deconvolution with Fusion. Blue region shown in detail in 8B below.

8 B. shows detail at full resolution from an MIP of the daisy pollen specimen. Right hand shows resolution and contrast improvement in individual pollen grain.

8 C. Single optical section from two channel daisy pollen Z series. Deconvolution enhances contrast, sharpens optical sectioning and provides clear channel separation in this thick bright specimen. Fine structures within the walls of the pollen grains become clearly visible. These punctate features are in the range 150-200 nm FWHM after deconvolution. Scale bar is 2 µm.
**REASON FIVE: Linearity in Dragonfly is better than 99%**

Point scanners do not quote this parameter

Linearity is important for quantitative studies where, for example, abundance of a fluorophore is used as a proxy for protein quantification or for monitoring dynamics processes like metabolic state or signalling.

Point scanners typically operate close to fluorophore excitation saturation (Tsien et al. 2006) and consequently exhibit a non-linear relationship between input power and photon emissions. In addition, as discussed above, PMTs are known to have significant non-linearities at high operating currents (Hamamatsu 2007) so that bright features appear dimmer. These two factors combine to create the typical power/signal curve obtained from a point scanning confocal (after Wang et al. 2005) shown in Figure 8. Operating at these power levels also shows high bleaching rates and phototoxicity: we will explore this further below.

In contrast, MSD micro-beam excitation powers are two or three orders of magnitude lower than the single beam instrument. This ensures that each micro-beam is well below saturation and fluorescence linearity is maintained in each of the probed volumes. Dragonfly EMCCD and sCMOS detectors exhibit >99% linearity over a wide dynamic range, operating in 16-bit readout modes and this combined with excitation in the linear range of fluorophores sets the instrument linearity.

![Experimental PS vs MSD Signal vs Power](image)

*Figure 9. Signal to Power relationship of point scanner (PS) versus microlens spinning disk (MSD) confocal (after Wang et al. 2005) with Andor iXon 897 EMCCD camera. Dragonfly uses a unique microlens dual spinning disk design, operating on the same principle as the unit compared by Wang, but with enhanced performance in terms of throughput, field of view and resolution.*
**REASON SIX: Dynamic Range**

Dragonfly up to 15-bit dynamic range

Saturation and non-linearity in point scanners, combine to produce low dynamic range data, which cannot capture the true range of intensities in a specimen. As an illustration of this point, the reader will note that point scanners often require two scans: one to capture dim signals and one to capture bright signals. Such demands add further to imaging time and bleaching effects. The images can be combined, but due to the low (sensitivity) QE of PMT detectors will never reproduce the dimmest features in the specimen with good signal to noise ratio.

In contrast, Dragonfly’s micro-beam scanning combined with high quantum efficiency (QE), linear detectors such as EMCCD or sCMOS, provides linear excitation and detection and achieves wide dynamic range imaging, supporting enhanced quantification. Typical dynamic range for the sCMOS detector is nearer 15 bits (30,000:1), based on the ratio of imaging detector full-well capacity to read noise. Figure 10 shows images of the same specimen acquired with Dragonfly and a high-performance point scanning system to illustrate the effect. True dynamic range in these point scanner images is typically limited to 8 or perhaps 10 bits (256:1 and 1024:1). In many cases images must be accumulated from multiple point-scanned images to yield these values. The Dragonfly equivalent is around 5,000:1 in this example. If the sCMOS sensor was driven closer to saturation this could be extended to 20,000:1 or higher.

![Figure 10](image)
REASON SEVEN: Photobleaching & Phototoxicity
Dragonfly is kinder to cells and has lower bleaching rates

Photobleaching of fluorophores is an inevitable consequence of fluorescence imaging. But it is a significant problem for point scanners because of the high intensities found in the focal volume. There is conjecture, and some evidence (Diaspro et al 2006), that multi-photon absorption events at point scanning power densities can accelerate bleaching; though earlier work (van der Engh and Farmer 1992) suggests that bleaching probability depends solely on the ratio of number of emitted photons to the average emission lifetime (in photons) of a fluorescent molecule. In either scenario photobleaching is considered as total loss of fluorescence of the molecule by oxidation (loss of an electron) either by reaction with the local environment or via triplet state reactions.

Some triplet state transitions do not result in loss of fluorescence, but their much longer lifetimes (0.1 to 1 µs) result in increased saturation effects. Oxidation and triplet state transitions can lead to the creation of free radicals e.g. reactive oxygen species (ROS) which are necessary in living specimens at relatively low levels. However, rapid localized ROS creation can be toxic and leads to abnormal cellular response and even to cell death. Once again Dragonfly’s micro-beam illumination approach, reduces photobleaching rate, saturation effects and slows the rate of ROS release in the probe volume.

As an example of imaging live specimens, where high speed and low phototoxicity are needed, Figure 11 shows an experiment where a genetically encoded calcium indicator is used to monitor spontaneous signalling in iPSC derived cardiomyocytes. This experiment proceeded for 15 minutes continuous imaging without obvious impact on cell health. The large field of view of Dragonfly was especially appreciated by the user who was interested in gathering statistical data on phenotypic behaviours of these cell lines.

Lower bleaching rate has a further benefit, especially when imaging thick or delicate specimens e.g. synaptic puncta in brain tissue. The high bleaching rate and lower sensitivity of a point scanner combine to destroy fluorescence in deeper layers of the specimen before they are addressed for imaging. Dragonfly’s gentler illumination and greater sensitivity combine to improve imaging quality and feasibility in such specimens.

Figure 11. Images from a time series of iPSC derived cardiomyocytes with a genetically encoded calcium indicator, GCaMP. Imaged on Dragonfly at 60X/1.2 magnification with 40um pinholes using iXon Ultra 888 (1024x1024) captured at 25fps. Courtesy: Dr Travis Hinson, The Pat and Jim Calhoun Cardiology Center, University of Connecticut Health Center & The Jackson Laboratory for Genomic Medicine.
**REASON EIGHT: Spectral Range**

Dragonfly allows extended NIR range up to 800 nm

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**Figure 12 A. Absorption spectral curve for tissue with variable proportions of water (orange) and lipid (blue)- in the range below 650 nm, the curves are coincident.**

Most confocal microscopes (including MSD) are limited to imaging the wavelength range 425–700 nm with excitation restricted to visible lasers ranging from 400–650 nm. This is due primarily to detector photocathode limitations, but also that lasers are coupled into the illumination system via single mode optical fibers. While a single mode fiber provides an effective point source for diffraction limited point scanning, it will not efficiently couple or transmit longer wavelengths. In contrast, Dragonfly uses a multimode optical fiber in its patented illumination system, Borealis™, where light from the solid-state laser engine is coupled into a 50 µm fiber, which can support wavelengths from 350–2000 nm. The remainder of Dragonfly optics are designed to support excitation and detection in the ranges 400–800 and 425–850 nm respectively.

The importance of this extended spectral range can be appreciated by studying the wavelength dependent absorption and scattering behavior of biological tissue. Figure 12 A. shows a profile (Jacques 2013) in which the absorption coefficient, μa (cm⁻¹) is shown as a function of wavelength: orange shows the outer envelope for water absorption, while blue that for high lipid (fat) content. Figure 12B. shows representative curves of optical scattering in tissue: the generally accepted terminology is that Rayleigh scattering refers to scattering by particles or mass density fluctuations much smaller than the wavelength of light, while Mie scattering refers to scattering by particles close or larger than the wavelength of light. Contributors to scattering are numerous and while it is possible to define generic equations combining Rayleigh and Mie, detailed spatial and biochemical structure make modelling very difficult. Direct measurements are also challenging, so that the range of estimates can be wide and different tissues show large variations with a combined range of 10–100 cm⁻¹. For simplicity in this paper, we show the envelope curves in Figure 12 B. to illustrate the intensity of the effects.

Note that the absorption and scattering profiles in Figure 12 are drawn on logarithmic scales: wavelengths 400–600 nm show absorption and scattering coefficients of more than an order of magnitude greater than the range 650–900 nm, so that working in the first NIR window is highly advantageous for imaging in-vivo and in tissue and organoid preparations but also in living preparations. Dragonfly’s wider spectral range supports NIR...
imaging for deeper penetration of native tissue as shown in Figure 13 and can be used to avoid auto-fluorescence which kills contrast in the visible range. The large spectral range also allows greater multiplexing of fluorophores in a single imaging acquisition protocol, which has increasing interest for e.g. transcriptome analysis. Sequential labelling cycles (Cai et al 2016) could be reduced with the larger number of imaging channels available.

Figure 13. Maximum intensity z-projection 13 A. and 3D volume rendering 13 B. of an aged rat brain slice containing oligodendrocytes and blood vessels fluorescently labeled with Invitrogen Alexa Fluor 488 dye and LI-COR® IRDye 800. Tissues like these accumulate auto-fluorescent lipofuscin pigments that create a high image background when excited and imaged with visible wavelengths.

The same z-projection 13 C. and volume rendering 13 D. of the brain slice when excited and imaged with infrared wavelengths show a greatly reduced auto-fluorescence background signal and a deeper imaging depth. Specimen kindly prepared by Dr. Claude Messier, University of Ottawa.
REASONS NINE and TEN: Uniformity and Stability

Borealis™ patented illumination technology

Two further significant benefits accrue from the design of the Borealis™ illumination system: first, coupling the laser into the large multimode fiber (≈200 times the area of a single mode fiber) provides higher damage threshold and improved long term stability. Unlike single mode fibers, normal levels of thermal and mechanical stress and strain have little impact on coupling efficiency with a large fiber. Second, a combination of high frequency laser homogenization and optical fiber selection to match the etendue or "optical extent" (Fischer and Tadic-Galeb 2000) of the microlens disk, deliver high throughput, low background and high spatial uniformity.

The application benefits of these features can be identified readily. Stability is important for longitudinal and comparative measurements as well as reduced instrument maintenance. Field experience with Borealis over more than 10 years, reveals virtually no maintenance involving re-alignment of lasers. Low background, as noted elsewhere, supports high sensitivity imaging, while illumination uniformity improves comparative quantification within the imaging field and benefits image stitching applications, which are increasingly important as we deal with larger specimens and tissues.

Point scanning confocal microscopes are not only limited in their spectral range by single mode fibers, but they can also suffer from excitation power drift. Consequently, careful monitoring and service of the laser power output will be required. This is also true for microlens spinning disk systems from other manufacturers, which use single mode fiber delivery systems. In the latter case, both uniformity and efficiency of illumination will be compromised because the manufacturer must trade throughput for uniformity, while managing the Gaussian irradiance profile typical of a single mode fiber laser beam delivery system.

Trade-offs applied in single mode excitation of microlens spinning disk and other camera-based confocals (e.g. Swept Field Confocal) require the expansion of the laser beam from a single mode (~3.5 µm diameter) spot to illuminate an aperture of somewhere between 12 and 25 mm: a scaling of about 3500 to 7000 times. In fact, the scaling is often many times more than this, so that a flatter beam profile is achieved, and this results in heavy losses of throughput e.g. 90%. Although diffractive optics and specialized remapping lenses can be used to correct the beam profile with lower losses, they are usually optimized at a single wavelength, limiting their application in multi-wavelength fluorescence microscopy. Hence, Dragonfly exceeds competitor single mode systems’ performance by a factor of at least two or three in both throughput and uniformity.

Figure 14: Uniformity and throughput: Dragonfly delivers bright uniform illumination, producing high quality data which improves analytical results in single and multifield measurements. Right hand images show 3x3 tiled montage (central plane from a z stack) images from a three colour plant section. Note the quality of image stitching where the resulting montage shows no obvious boundaries. Dragonfly Borealis™ illumination, typical roll-off is ~10% - wavelength and objective dependent.
**REASON ELEVEN: Super-resolution**

Direct Stochastic Optical Reconstruction Microscopy – dSTORM

Dragonfly supports dSTORM (Heilemann et al 2009), a localization method in which the blinking of organic dyes is enhanced by reductant substrates such as Glucose oxidase and MEA (mercaptorethylamine). As with all localization-based super-resolution methods, dSTORM excites a sparse sub-population of single molecules in a time series and identifies their position to sub-pixel precision by fitting a (Gaussian) point spread function to each detected fluorophore. Accumulation of the localizations creates a super-resolution pointilliste image. Accuracy depends on SNR (and background) so high laser power densities (>1 kW cm-2) are needed to extract a high number of photons from the molecule in each frame and return molecules to a dark state quickly.

To support this kind of experiment, the Dragonfly Borealis™ illumination system is designed with four motorized illumination zooms from 1X to 6X (1X–36X power density). This allows the same laser used for confocal, widefield and TIRF to be applied to dSTORM imaging. The benefits of using flat field illumination, like Borealis™, for super-resolution have recently been emphasized by Douglass et al (2016).

See Figures 15 and 16 for example data sets from a dSTORM experiment performed with Dragonfly.

Recently researchers have developed probes whose fluorescence blinking results from transient DNA-DNA interactions (Jungmann et al 2014): DNA-Paint requires lower power densities because the blinking rate is not driven by bleaching molecules into dark states, but by the relative affinity between probe and target. This technique offers significant promise and is well matched to Dragonfly capabilities.

To explore the 3rd dimension in super-resolution localization, Dragonfly provides a motorized astigmatic lens to create a calibrated asymmetric distortion of the single molecule PSF, which varies with axial defocus (Mlodzianoski et al 2009). The asymmetry encodes positive and negative axial offset differentially in X and Y dimensions and is supported in many third-party localization analysis tools e.g. Thunderstorm (Ovesny et al 2014).

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**Figure 15.** T cell labelled with an AF647-tagged surface receptor antibody was imaged with Dragonfly and Borealis® wide-field illumination at power density 4 to maximize signal and blinking frequency. 10,000 frames were acquired with Andor iXon 888 cropped at 512x512 pixels, Leica 60X/1.45 oil objective. Reconstruction was computed with ThunderSTORM (Ovesny et al 2014), RCC drift correction was applied. Image courtesy of Amgen Oncology Department.

**Figure 16.** U2OS cell labelled with AF647-anti-tubulin was imaged with Dragonfly and Borealis® wide-field illumination at power density 4 to maximize signal and blinking frequency. 10,000 frames were acquired with Andor iXon 888 cropped at 512x512 pixels, Leica 60X/1.45 oil objective. Reconstruction was computed with ThunderSTORM (Ovesny et al 2014), RCC drift correction was applied. Image courtesy of Amgen Genome Analysis Unit Department.
REASON TWELVE: **SRRF-Stream**  
Super Resolution Radial Fluctuations

Stochastic fluctuation analysis (SFA), such as SOFI (Dertinger 2009) and SRRF (Gustafsson et al 2016), depends on the analysis of image time series. Usually short exposures are used to enable relatively fast sampling. The value assigned to an output pixel depends on both the original brightness and the correlation coefficient resulting from analysis of temporal intensity fluctuations in the pixel. Background tends to be poorly correlated and so significant gains in contrast can be won. In SOFI, improved resolution is derived from higher order cumulants: these are statistical moments of the time series data. In SRRF, resolution gains are achieved from continuous interpolation of the radiality field. Radiality is computed from the local radial gradient (Parthasarathy 2012) and B-spline interpolation onto a super-sampled pixel grid. High levels of radial symmetry are indicative of the locale of fluorescence emitters (see Figure 17), but in very densely labelled regions, it becomes impossible to distinguish between emitters and artifacts can arise. However, with care, SRRF is applicable to widefield, confocal and TIRF image data. In terms of resolution and light dose SFA is competitive with structured illumination microscopy (SIM) (Gustafsson M 2000).

In SRRF, the number of images per sequence can be varied to trade spatial and temporal resolution. This is especially useful for live cell studies where phototoxicity is a concern. Typically, 10 times the light dose is required to double resolution. The SRRF algorithm can be adapted to dSTORM data as well as short time bursts, subject to good signal to background ratio, and so it provides a flexible adjunct to the super-resolution toolbox. To exploit SRRF optimally, we have created SRRF-Stream, a GPU-accelerated implementation which streams images from the camera direct to GPU for near real-time processing. SRRF-Stream is implemented with iXon Ultra and Sona cameras (Browne et al 2017).

Integration into Dragonfly/Fusion was released in the fall of 2017. To appreciate the speed of SRRF-Stream refer to Table 3, where processing times are shown to be in line with acquisition times and hence “real time” super-resolution performance.

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**Figure 17.** The concept of radial symmetry for localization of fluorescent emitters (after Parthasarathy). In SRRF, the degree of radial symmetry in local intensity fluctuations is referred to as ‘radiality’ and radiality is interpreted as the probability of the presence of an emitter. Hence the temporal correlation of radiality on a super-sampled grid provides a weighted super-resolution estimate of the emitter distribution.
Experience with SRRF-enabled cameras and Dragonfly is encouraging and we present two examples here. In Figure 18 A we explore resolution vs number of frames processed in a live cell TIRF time series. Comparing conventional TIRF with SRRF-TIRF images of microtubule dynamics show a significant reduction in background, while mean lateral resolution, measured by FRC (Fourier ring correlation) improves asymptotically to around 100 nm or better after 1000 frames.

<table>
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<tr>
<th>Nvidia GPU</th>
<th>Data size uint16</th>
<th>SRRF-Stream ms</th>
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Looking at FRC convergence in sub-areas of the image and referring to the blue line in Figure 18 A, we see that some sub-areas of the image achieve sub-100 nm resolution after around 100 frames. This suggests that dynamic live cell imaging can achieve this resolution at around 1 composite frame per second under the right conditions. Note however, that in very bright regions of the image, artifacts can be produced.

Figure 18 A. The evolution of FRC (Fourier Ring Correlation) resolution with number of frames in the SRRF-Stream time series. Data was acquired with an iXon EMCCD at 10 ms exposure, running at ~100 fps using a Nikon 60X/1.49 TIRF objective, microtubules visualized with GFP excited at 488 nm. The image was divided into 32x32 pixel sub-arrays and FRC computed on each. Mean (red) shows the average from all ROI’s analyzed, while Minimum (blue) shows the best resolution of the ROI group.

18 B. SRRF functions across modalities and fluorophores. Averaged widefield image of fixed cell specimen with anti-tubulin label shown in blue. Below is the SRRF-Stream result from processing the same 100 frames Data acquired on Dragonfly with iXon Ultra 888, Nikon 60X/1.49 TIRF lens 2X magnification.
In the next example we tested the SRRF algorithm with fixed tissue and conventional fluorophores with confocal imaging on Dragonfly. Data in Figure 19 is derived from 100 frames at 512x512 from iXon Ultra 888 with high SNR at exposure time 30 ms and pixel size ~196 nm in three fluorescent channels from a fixed kidney section. The SRRF-Stream algorithm was applied to the data series with a pixel magnification of 8 times, resulting in an image of 4096x4096 with pixels ~25 nm.

As can be observed the striation in vessel walls (red channel) which might be considered as ambiguously separated features in the confocal images are clearly separated in the SRRF images. Using the full-width half height ruler, commonly applied in the literature, the feature width is measured at ~100 nm.

Figure 20, shows data shared with permission of Amgen Inc., in which lipid droplets are highlighted in Hep3B cells acquired with and without SRRF processing. SRRF reveals fine structures within the droplets and in the chromatin architecture.
Discussion

Dragonfly is a powerful, flexible tool which can be adapted to your questions than individual instruments. We have discussed strengths and weakness of both technologies and contrasted Dragonfly with previous generation MSD. Some may argue that we should consider light sheet as a new and competing technology, but such a comparison is difficult because light sheet is still an emergent technology and not widely available as a standard tool, but no doubt this technology will mature. Dragonfly does not offer spectral imaging, at least for now, and if this is an important tool for your research, we ask you to consider the wider spectral range as a means of increasing multiplex, if that is the goal. Of course, there is no perfect confocal microscope, but we summarize the performance factors we have considered here, with Figure 21 in which the bullseye represents perfection. With this, we suggest that Dragonfly marks a significant step towards the goal of improving performance, throughput and data quality. These are key factors in evaluating instrumentation for the future of research in the life sciences.

Life science research has entered a new era: as understanding deepens, questions become more complex and require imaging tools which can bridge scales from nm to mm. Speed, throughput, resolution and high volumes of quantifiable data are essential components in this endeavour. Dragonfly is designed as a high-resolution imaging platform which delivers performance and value to both multi-user and single investigator labs. Dragonfly achieves performance across multiple imaging modes without compromise because the fundamental requirements are common: mechanical and optical stability; efficient and well-controlled illumination; optimized detection pathways; careful management of stray light; sensitive detectors; and high performance, easy to use software. Understanding these principles allowed us to develop a product which exceeds or challenges competitive products in every feature of performance.

In this white paper, we have compared Dragonfly with point scanning and focused on technologies rather than individual instruments. We have discussed strengths and weakness of both technologies and contrasted Dragonfly with previous generation MSD. Some may argue that we should consider light sheet as a new and competing technology, but such a comparison is difficult because light sheet is still an emergent technology and not widely available as a standard tool, but no doubt this technology will mature. Dragonfly does not offer spectral imaging, at least for now, and if this is an important tool for your research, we ask you to consider the wider spectral range as a means of increasing multiplex, if that is the goal. Of course, there is no perfect confocal microscope, but we summarize the performance factors we have considered here, with Figure 21 in which the bullseye represents perfection. With this, we suggest that Dragonfly marks a significant step towards the goal of improving performance, throughput and data quality. These are key factors in evaluating instrumentation for the future of research in the life sciences.
Let **Dragonfly** be the next confocal system in your lab or core facility, and contact Andor for more information or to arrange a demonstration!

Dragonfly is an extremely capable confocal, widefield and TIRF imaging platform and it can be equipped for two modes of super-resolution imaging. GPU-accelerated image processing and real-time 4D visualization are key tools for modern research, enabling rapid exploration and interpretation. This flexibility delivers the functionality you need to ask biological questions in the right context, and that may mean expressing the biology of interest in more than one model organism or specimen preparation. Dragonfly is uniquely adaptable to these studies and specimen types. While we have focused on confocal performance versus point scanning systems here, the broader capabilities are summarized in Table 4, where we show which Dragonfly features benefit the kinds of specimen types in wide spread use today.

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<th>Specimen type</th>
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*Table 4. shows how Dragonfly features map onto specific kinds of specimen and imaging experiment.*


References
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